Design and optimization of patient-specific, pediatric laryngoscopes

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Abstract: Place a brief summary of your work here. Do not use more than 100 words. 3D printing is of outstanding importance in medical engineering and has been growing continuously in recent years. From prostheses and soft implants to matrices for tissue engineering, additive manufacturing has decisive advantages for medicine. The scientific conference AMMM 2019 brings together engineers, scientists and technicians with physicians and entrepreneurs to discuss the latest achievements in 3D printing development for medicine.

# I. Introduction

* Laryngoscopes were first introduced in…
* The most modern laryngoscopes are…
* There are such things as disposable laryngoscopes…
* Laryngoscope blades vary per age group, but there is only # options for pediatrics…
* Difficulties with intubation represent the main cause of pediatric, anesthesia-related morbidities and mortality [1]. Even in scenarios where difficult intubations are expected, anesthesiologists know to have “all the equipment to hand,” which translates into a clutter of devices and cost inefficiencies [2].

The design of patient-specific devices requires several steps…

# II. Material and methods

## II.I. Patient Data

The raw patient data should be geometry of the tissue and bone in the patient, leaving the airway of the patient hollow. In most segmentation software, this is a simple task, and can even be done in Houdini, using our custom segmentation software, to avoid using different software.

## II.II. Patient Data

We used Houdini FX, a VFX software traditionally used in the film and games industries to create a process for rapidly segmenting airways from patient geometry, finding the average path through that airway, then using that data to procedurally design a laryngoscope that is sized to perfectly fit the patient it has been designed for. This process starts with importing patient data, which can be created using any software (including Houdini with our customized DICOM toolset built for Houdini). Next, the data can be segmented inside of Houdini to isolate the negative space of the patient’s airway. After that a solver is ran to determine the path and width of the airway, before finally extruding the tool along the toolpath created from the patient data, and fabricating the new device using 3D printing technologies. Figure 1, below, shows this process broken into several distinct parts, for importing patient data, refining patient data, finding a close bounding shape, segmenting the airway from the rest of the patient data, finding the center line, which can be exported for use in other cad software, or applied to the tool profile in Houdini to create a device.

Figure 1: Process and Program Diagram

## II.III. Segmentation

The segmentation step involves creating a shell around the base geometry, using a shrink-wrap operation, and then using a subtraction operation to cut the source patient geometry from the shell geometry. This will leave the airway, and any other empty space inside of the patient data geometry, allowing easy removal of the disconnected parts, leaving only the negative space of the airway.

## II.IV. Pathfinding

After the airway volume has been segmented, there are two options for finding its center path, one being the use of a modified space colonization algorithm, and the other using Houdini’s native find shortest path node.

The space colonization method, takes an input point near the front of the volume, where the mouth would be, and using a point cloud defined inside of the airway’s volume to organically grow a path through the airway, which can be averaged to find a close approximation of the curvature of the airway.

The other option is to select a group of points at the mouth, and another group at the end of the airway, and to use find the shortest path between the two groups using a point cloud similar to the one used for space colonization method, and averaging the paths to find a centerline.

## II.V. Part Design

Using the airway path designed above, you can extrude and loft a tool shape along this path to create a laryngoscope that will follow the path of the airway, and can be easily and quickly customized to any patient.

## II.VI. Fabrication

Since this part was designed in a digital space, it can be easily exported for creation on a 3D printer. This methodology would allow for the rapid creation of one-time-use medical devices that could be designed on an as needed basis for patients as they enter a hospital with minimal wait time.

# III. Results and discussion

Table 1: Results

|  |  |  |
| --- | --- | --- |
| **Segmentation** | | |
| **Thresholding** | | |
| **Patient** | **Value** | **Unit** |
| 1 | 24, Bold, Calibri | Title |
| 2 | 12, Bold, Calibri | Authors |
| 3 | 12, Italic, Calibri | Affiliation |
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# IV. Conclusions

Although a conclusion may review the main points of the paper, do not replicate the abstract as the conclusion. A conclusion might elaborate on the importance of the work or suggest applications and extensions.

### Acknowledgments

##### The preferred spelling of the word “acknowledgment” in America is without an “e” after the “g”. Avoid the stilted expression, “One of us (R. B. G.) thanks . . .” Instead, try “R. B. G. thanks”.

### Author’s statement

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#### References

[1] M. Weiss and T. Engelhardt, "Proposal for the management of the unexpected difficult pediatric airway," *Pediatric Anesthesia,* no. 20, pp. 454-464, 2010.

[2] R. W. M. Walker and J. Ellwood, "The Management of difficult intubation in children," *Pediatric Anesthesia,* no. 19, pp. 77-87, 2009.